

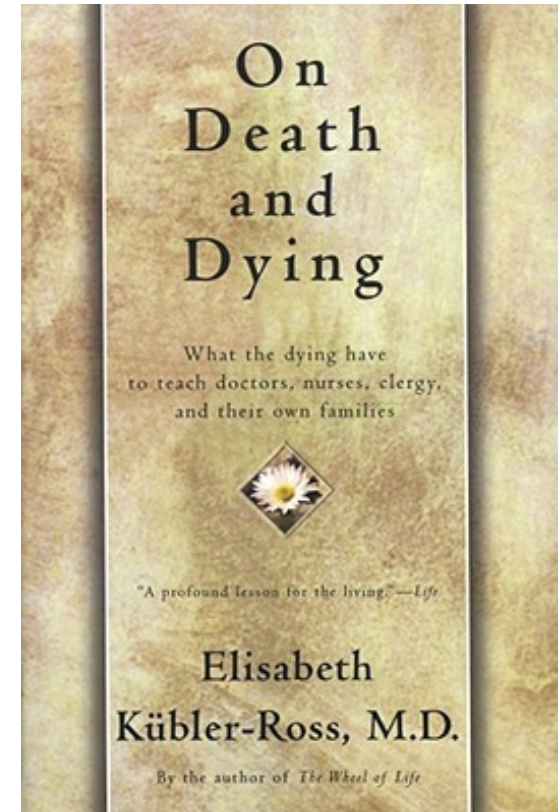
# AUTO-CAAS: Model-Based Fault Prediction and Diagnosis of Automotive Software

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# Elevator pitch

- Bug fixing is like dying:  
**Denial** → Anger → Acceptance
- Demonstrating **probability** and **severity** to facilitate the process
- Using **machine learning** to capture all failing scenarios
- Context: **AUTOSAR** software



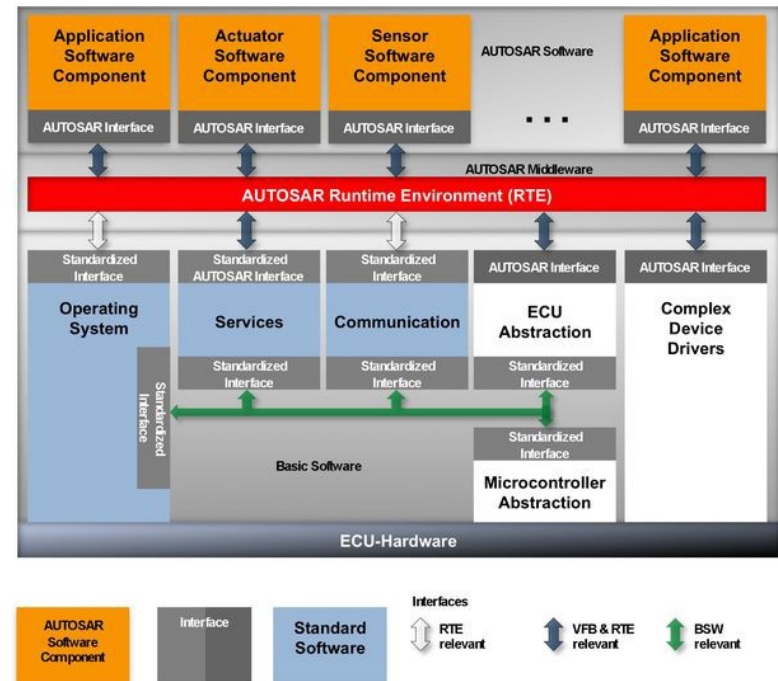
# Partners & Funding

- Halmstad University  
Research in **model-based testing** and software verification
- Quviq A.B., Sweden  
Model-based testing tool **QuickCheck**, **AUTOSAR models** and testing expertise
- ArcCore A.B., Sweden  
**AUTOSAR development environment**, open source **AUTOSAR implementation**
- Funded by



# AUTOSAR

- A comprehensive standard for building **automotive software**
- In particular, description of **basic software components / libraries**
- ~3k pages of text
- Examples:  
CAN-bus stack, FlexRay stack,  
memory access interfaces,  
hardware abstraction  
(e.g. PWM / ADC), ...



# Motivation

- Automotive Open System Architecture – AUTOSAR
- To enable pluggable components and **multiple vendors**
- Room for **interpretation and optimisation**
  - Intentional and inadvertent specification loopholes
  - Specific implementations differ  
(from each other and from the spec)
- Results in **non-conformant components**
- Can lead to **serious problems** in integration
- Research question – measure the severity, find the **consequences**

# Goals

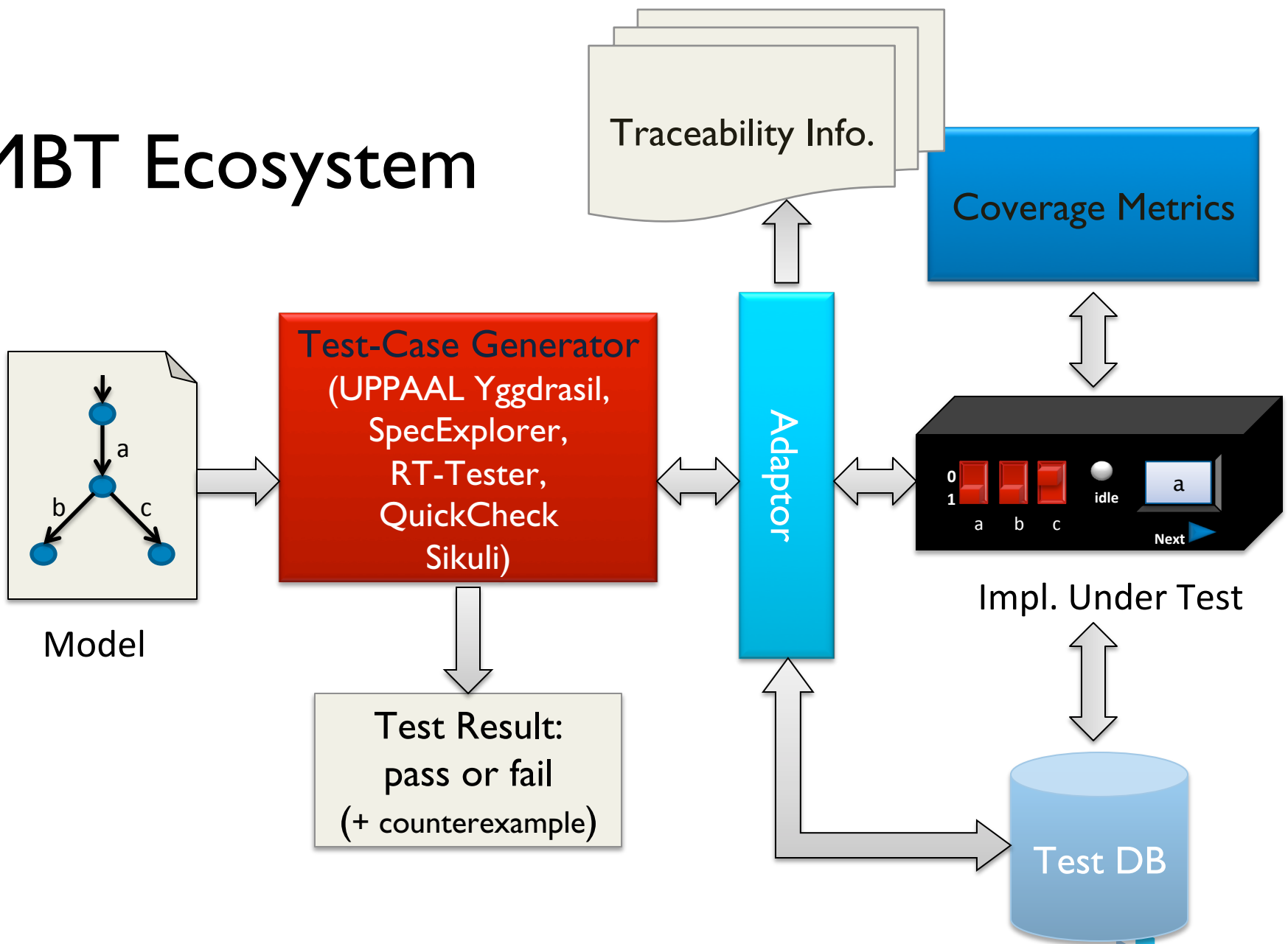
In the context of the AUTOSAR standard:

- 1 Measure the severity of deviations in **non-conformant components**; show how a selection in a given (complex) system leads to a failure (bottom-up)
- 2 Given a **failure** of the system and the knowledge of deviations in components, identify the **root cause** (top-down)

# Means

- 1 Model-Based Testing (MBT)
- 2 Machine learning techniques
- 3 Symbolic execution

# MBT Ecosystem





# Model Based Testing with QuickCheck

- Erlang based tool for guided random **test generation** Based
- on a **state-full model / specification**
- Can test functions in separation, but also their **interaction**
- Very snappy and cool! 😊
- Probably more about this in John's talk

# The First Task

- 1 Detect and classify non-conformances
- 2 Summarise / formalise them

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- 1 Detect and classify non-conformances
  - 2 Generalize and summarise them
- Problem 1 is relatively easy:
    - Use QuickCheck and AUTOSAR models to find concrete failures
  - Part 2 is to quickly detect whether a particular behaviour observed later falls into the non-conformance, a formal description of sorts

# Specification of Non-Conformance

- **Negative model** of the component
- I.e. a description of what the non-conformance does
- Saturated to only that behaviour;  
other (correct) behaviours not in scope
- Can be **parametric** to further differentiate kinds of a particular non-conformance
- [What QuickCheck actually does for implementation variants]

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- [What QuickCheck actually does for implementation variants]

## Question 1

How to generate it (semi-)automatically out of a (failing) test?

# Constructing Negative Models

- Automata learning
- Normally used to learn the models of correct, black-box systems
- Now learn about failures / non-conformances
- Not so straightforward:
  - How can we be sure that we learn about **one** failure?
  - How to remove “noise” during learning?
  - How to keep the input alphabet small?
- **LearnLib**: Automata Learning framework implemented in Java (powerful and unfortunately complex)
- Interface LearnLib to QuickCheck

[S. Kunze et al., Generation of Failure Models through Automata Learning, WASA 2016]

# Example

```
/* Given the requested size of a buffer, return  
the available space. */
```

```
size_t get_buffer_size(size_t req_size);
```

```
/* Return the pointer to the array. */
```

```
uint8* get_buffer_array();
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What happens when:

- The requested size is 0 or negative?
- The available space is smaller than the requested size?
- The pointer?

Or even...



# Example

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/* Given the requested size of a buffer, return
   the available space. */
size_t get_buffer_size(size_t req_size);

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uint8* get_buffer_array();
```

What happens when:

- The requested size is 0 or negative?
- The available space is smaller than the requested size?
- The pointer?
- Or even... what is actually returned in normal conditions?  
Requested size or available space?

# Where is the Problem?

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- Fine as long the surrounding environment is aware of the particular choice...
- When intermixing implementations things **will go bad!**
- Typical problems:
  - Treatment of **corner cases**
  - Indexes and timing off by one
  - ...

# Symbolic Execution

- Run the program **on symbols** instead of concrete data
- “**Split**” the running on every **decision point**
- Collect the different **execution paths**
- Each path is defined by **constraints** over the program data
- **Tricky bits** are library function calls, iterations, and recursion

# Symbolic Execution Applications

- Popular in theorem proving / program logics for **formal verification** of programs
- Can be applied to the code or the model (QuickCheck models are **executable**)

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- Popular in theorem proving / program logics for **formal verification** of programs
- Can be applied to the code or the model (QuickCheck models are **executable**)
- Can be then used for **Concolic Testing** (**Concrete** / **Symbolic**)
  - The set of execution paths provide **test partitioning**
  - Test data generated by **constraint solving**

# Further Tasks

## Question 2

Can a non-conformant component cause trouble?



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# Further Tasks

## Question 2

Can a non-conformant component cause trouble?

```
/* Given the requested size of a buffer, return  
the available space. */  
size_t get_buffer_size(size_t req_size);
```

- 1 Return **-1** when requesting too much
- 2 Return **capacity** when requesting too much

# What Can Go Wrong?

```
if(get_buffer_size(128) <= 0) {  
    /* Bail out / recover */  
} else {  
    /* Store 128 bytes of data in the buffer */  
}
```

Behaviour **2** of `get_buffer_size` will cause a **segmentation fault!**

```
if(get_buffer_size(128) < 128) {  
    /* Bail out / recover */  
} else { ... }
```

Safe for both behaviours! How about other cases, especially **generated software?**

# Further Tasks

## Question 3

When the system fails / crashes – was it caused by a non-conformant component and if so, which one?

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When the system fails / crashes – was it caused by a non-conformant component and if so, which one?

First idea:

- Perform **run-time checking** of sorts
- Record traces of function calls and their parameters
- Check if they fall within the non-conformant model (specification) of any of the components
- Could be possibly done on a live system (ECU)

# Conclusions

- **Model-based testing**: an effective method of **bug hunting**
- Bug fixing: a social process
- Demonstrating **probability** and **severity** of a bug facilitates the process:
  - machine learning to generalize the failing test case
  - symbolic execution to demonstrate bigger failures

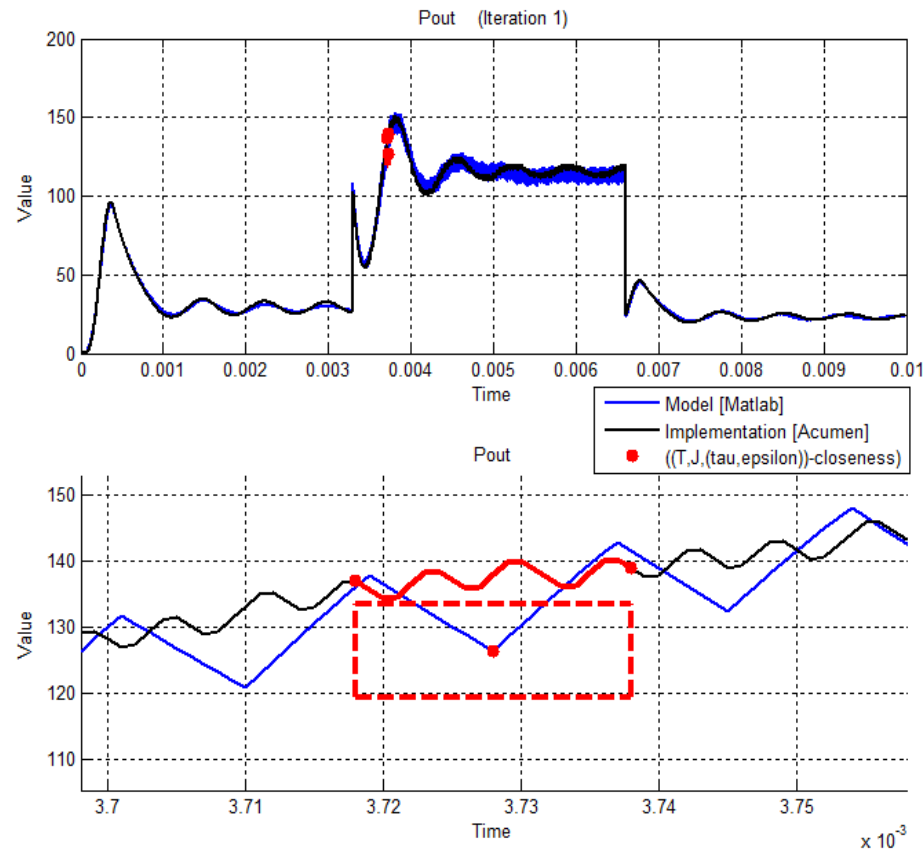
# Next Steps

- Apply symbolic execution to search for consequences and to diagnose failures
- Apply to more realistic case studies (Arctic Studio implementations, fault injections)
- Implement necessary extensions in QuickCheck

# MBT for Cyber-Physical Systems

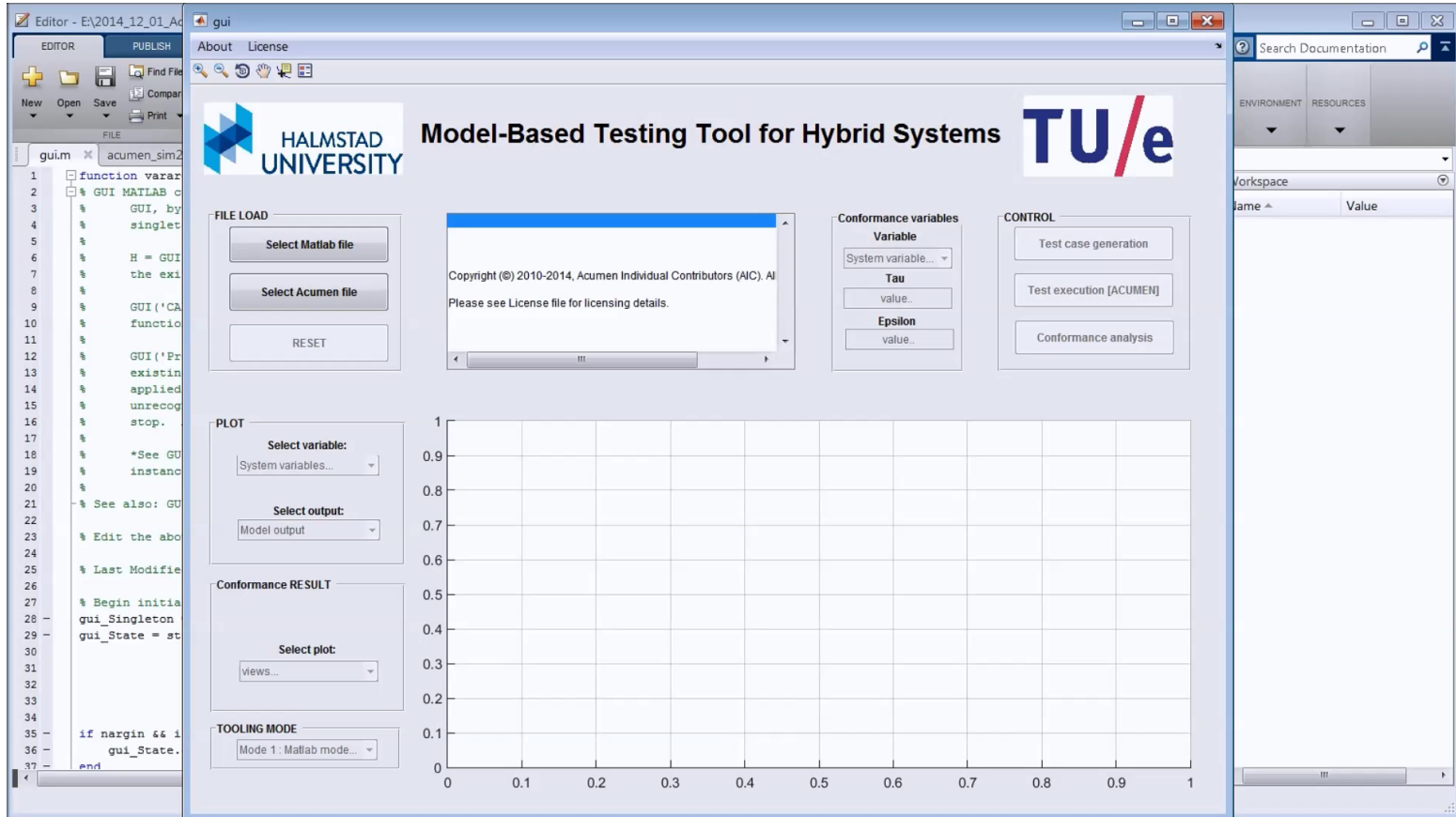
## Challenges:

- Modeling system dynamics (differential equations, accuracy of numerics)
- Sampling inputs and outputs, approximate conformance (in time and value)
- Coverage





# MBT for Cyber-Physical Systems



[Aerts, Reniers, MRM.  
Tool Prototype for Model-Based Testing of  
Cyber-Physical Systems, ICTAC 2015]

# 6<sup>th</sup> Halmstad Summer School on Testing

[http://ceres.hh.se/HSST\\_2016](http://ceres.hh.se/HSST_2016)



**Dino Distefano**  
FaceBook and  
Queen Mary U.



**Alastair Donaldson**  
Imperial College



**Jeff Offutt**  
George Mason U.



**Marielle Stoelinga**  
U. Twente



**Alexandre Petrenko**  
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**Per Runesson**  
Lund U.

# Thank You!

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